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~~#Unit 3: Doing Motion Planning programmatically ROS  
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Basics Concepts ROS BASICS IN 5 DAYS #1 -  
Course Overview Introduction ROS Robotic  
Challenge Solve | Basic ROS Learning Week day 5 |  
Turtlebot2 Basic ROS Learning Week - Day 1: Linux for  
Robotics [ROS Q] 138 - How to set a~~

~~sequence of goals in MoveIt for a manipulator? **Basic  
ROS Learning Week - Day 5: Program a robot**~~

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Planning - Part 1 MoveIt Training for Beginners Ros  
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Build with ROS and Nvidia Jetson Nano ROS | TurtleBot  
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~~Trajectory Execution of a robot manipulator using ROS  
MoveIt and Arduino. ROS kinetic tutorial #05 ROS  
topic, nodes, messages P1 Custom MESSAGES in ROS  
| Tutorial #5 | ROS and Raspberry Pi **Robot**~~

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Basic ROS Learning Week - Day 3: ROS Basic concepts  
(packages, nodes, launches...) **ROS NAVIGATION IN**~~

~~**5 DAYS #3 - Robot Localization** ROS NAVIGATION  
IN 5 DAYS #4 - Path Planning - Part 2 ROS Learning  
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ROS Manipulation is the term used to refer to any robot that manipulates something in its environment. The main goal of this Course is to teach you the basic tools you need to know in order to be able to understand how ROS Manipulation works, and teach you how to implement it for any manipulator robot.

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